ICRA 2021 Workshop on Representing and Manipulating Deformable Objects

Coffee break
We will resume at 11:15 GMT+00
Up Next:

11:15 – 11:45  Zackory M. Erickson: Physics-based Cloth Simulation and Learning Towards Robotic Caregiving

11:45 – 12:15  Júlia Borràs Sol: On analyzing and representing cloth manipulation tasks

12:15 – 12:45  Open discussion round with
• David Navarro-Alarcon
• Xiang Li
• Guillem Alenyà
• Júlia Borràs
• Yiannis Karayiannidis

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https://deformable-workshop.github.io/icra2021/
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### Júlia Borràs Sol

Researcher and Vice-Director

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Discussion topics:

- Scalability of the approaches: are we ready to deal with real world deformable objects?
- Boundary between control theory and learning: where should we use learning? How and when should we combine these two worlds?

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