



# ICRA 2021 Workshop on Representing and Manipulating Deformable Objects

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Coffee break  
We will resume at 11:15 GMT+00

# ICRA 2021 RMDO Workshop – Coffee break

## Up Next:

<b>11:15 – 11:45</b>	<b>Zackory M. Erickson:</b> Physics-based Cloth Simulation and Learning Towards Robotic Caregiving
<b>11:45 – 12:15</b>	<b>Júlia Borràs Sol:</b> On analyzing and representing cloth manipulation tasks
<b>12:15 – 12:45</b>	<b>Open discussion round with</b> <ul style="list-style-type: none"> <li>• David Navarro-Alarcon</li> <li>• Xiang Li</li> <li>• Guillem Alenyà</li> <li>• Júlia Borràs</li> <li>• Yiannis Karayiannidis</li> </ul>



### Zackory M. Erickson

PhD candidate

Georgia Institute of Technology, USA

Will be joining CMU this Fall as an Assistant Professor in the Robotics Institute



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<https://deformable-workshop.github.io/icra2021/>

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### **Júlia Borràs Sol**

Researcher and Vice-Director

Institut de Robotica i Informàtica Industrial, Spain



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## Discussion topics:

- Scalability of the approaches: are we ready to deal with real world deformable objects?
- Boundary between control theory and learning: where should we use learning? How and when should we combine these two worlds?



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